AstroNavigation

A celestial navigation program for a Palm OS® computer

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AstroNavigation

Content

1. What you get	3
2. Something about your input	4
3. The menu	5
3.1. Compute a position	5
3.2. To find a star	7
3.3. (De)activate your sights	9
3.4. Rating the sights	9
3.5. Changing your recorded sights	10
3.6. Clearing your sights	10
3.7. Computing a star's bearing	10
3.8. Computing a course and distance	11
3.9. Computing a new position	11
3.10. Noon	12
3.11. Change the year	12
4. High altitude sights	13
5. The average of sights	14
Appendix	15
Some examples	15
Addenda	17
Acknowledgements	17

2

1. What you get

The pastroe.zip file includes the program AstroNav. It also includes a copy of MathLib.prc. Please move the programs to your Pilot. Clear an old version first. The program version is compiled for Palm OS® 2.0 and higher.

2. Something about your input

The data input for a program is always a problem if you have to input degrees, minutes, seconds or time. To make it easier the data are separeted by space (stroke),

e.g. to enter 12 degrees 34.5 minutes do this 12<space>34.5 for the time 12:45:56 12<space>45<space>56

All times are in UTC (universal time coordinated).

3. The menu

When you start your program you will see the following on your display:

Astronavigation 🚯					
sun	(sight)(sights)			
moon	(<u>fix</u>)(clear)			
stars	Vear V	chanae)			
venus	$ \longrightarrow $				
mars					
jupiter	(<u>course</u>)				
saturn	(destination)				
year sights	2000 0 (0)				

On the left are the celestial bodies the program can use while centre and left display the operations the program can perform.

3.1. Compute a position

The program uses its own internal year to allow you to work sample sight reductions. However, before commencing a reduction ensure that the correct date is set. The sample problems in this documentation all use the year 1990. Set the appropriate year by first selecting 'year' from the middle column.

To reduce a sight or calculate a fix choose a star (from the left column) and start the calculation of your first sight (select 'sight').

Example:

We will reduce two sights and calculate the fix using the following sample data. (Please set the year for the examples to 1990.)

D.R.	13 53'N
	44 39'W
1. sight	sun 16.12.1990 UTC 10:49:06
	down 19 18.6' no index error
	height 2 m
2. sight	sun 16.12.1990 UTC 14:37:10
	down 52 28.2' no index error
	height 2 m
	run distance course 270 , 19 nm

These are sun sights so select 'Sun' and then 'Sight' from the main menu.

Now you can input your data for the first sight. First input your D.R. (Dead Reckoning) position. Remember the input terms: first the degrees then a space followed by the minutes.

Then select north or south. North is the default. 2001/09/05

Do the same with the longitude. Use the 'old' button to input an old fix or destination in these fields.

The date follows. Please input only month and day. The year is set in the main menu.

The time is the next data. Please remember the input terms.

Now input the sextant angle. If you work with the sun or the moon select the type of sight.

Input the correction now. The defaults are typical for sailors. If your index error is negative, you have to put an '-' in front of the minutes. The height of the eyes are in metres.

The buttons in the form 'sights' mean:

- down/up or normal = (lower/upper limb) natural horizon
- 0 = artificial horizon (the height is not used)
- 2 = artificial horizon with double angle (using lake as mirror)
- S = short horizon (dip short) includes down/up when needed, add the distance to horizon in nm

To change between date format (dd.mm./mm.dd.) or the height (m/ft) press the menu button and select your favorite.

Now push the 'compute' buttom.

	Astronavigation 🚯
sun	
lat	13.53 N.S. (old)
long	44.39 W E
date	12 16 1990 (mm.dd.)
UTC	10 49 6
sexta	nt <u>1918.6</u> down up 0 2 5
indexe	error 0.0
height	: m.2 <u>.0</u> nm 0.1 to
	azimut 121.3 °
(Ok)	cancel (?) (compute)

Please wait for the computing. You will see the miles away or towards the star and the computered azimut. The miles should be very small. If the value seems too big there will be an input error or your sextant angle needs to be controlled. If everything is ok press the 'Ok' buttom. You are back to the main menu now.

For the second sight you can choose all stars again. The mask (inpout form) is like the first one but there is no position. You have to input the running values angle and distance.

The new sight is computed from the new position.

After two sights you can visit your position. Please press the 'fix' buttom in the main menu. The output looks like this:

2001/09/05

	Astronavigation	6
sight	s 2 of 2	
12/1	6/1990	
14:37	:10	
D.R.	13° 53.0' N	
	44° 58.6' W	
fi×	13° 42.5' N	
	45° 5.0' W	
BV	210.7° 12.1 nm	
(Ok)	l (save)	
ι <u></u>	;	

The D.R. is shown from your last postion. The correction is computed (BV) from here.

You may save your values to the memopad as a log file.

You can add now another sight or clean up everything. If you do nothing the sight will be saved so when you start the program again you still have this position. More examples are below in this document.

3.2. To find a star

In the twilight often you have the chance to take a sight of a star but you don't know which star it is. In this case you can select 'unknown' as the star name (default) and input the bearing of the star. The program will determine the star but it takes a little time since it must make the computation for all the candidate stars and planets. So please wait for the answer.

The other inputs are the same as for the sun.

For example:

D.R.	13 55 N		
1 gight	44 31 W	16 12 1000	UTC 0.26.10
I. SIGIIC	bearing 80	sextant 44	36.4'
2. sight	unknown star bearing 350	16.12.1990 sextant 42	UTC 8:30:30 4.4'
	no run distanc	ce	





The program always computes all stars if unknown is selected. Selection is then made from the nearest of the 80 stars or planets but only you can determine if the output is correct or not.

The output for this example should be:

2 sig 16.12 8:30:	ghts 2.1990 30			
pos	lat:	13	55.0	Ν
	long:	44	31.0	W
fix	lat:	13	49.6	Ν
	long:	44	39.8	W
BV	237,5	10.1	nm	

The stars in this case are Arcturus and Dubhe.

You can try an other sight (upto 20):

3.	sight	unkown star	16.12.1990	UTC 8:38:40
		bearing 270	sextant 5	57 19.2'
		no index erro	or, height 2	m
		no run distan	ice	

The output is:

3 sights 16.12.1990							
8:38:	40						
pos	lat:	13	55.0	Ν			
	long:	44	31.0	W			
fix	lat:	13	48.8	Ν			
	long:	44	37.6	W			
BV	225.9	8.	8 nm				

The unknown star was now the planet Jupiter.

There are no Greek characters for stars in the program I have used th following:

а	alpha	е	epsilon	i	iota	n	nu	r	rho	v	phi
b	beta	f	zeta	k	kappa	q	xi	s	sigma	х	chi
С	gamma	g	eta	1	lambda	0	omicron	t	tau	У	psi

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d delta h theta m mu p pi u upsilon z omega

3.3. (De)activate your sights

You can control which of your sights are used to compute the fix. If you want to have a sight not included on the fix, deselect that sight in the 'sights' screen and it will not be used for the fix. You can later reactivate this sight if desired.

A	Astronavigation 🚯					
sight	3 jupiter					
D.R.	13° 55.0' N					
	44° 31.0' W					
date	12/16/1990					
	8:38:40					
sextant	57° 19.2'					
azimut	280.6					
nm	3.2 to					
	🕑 compute					
_						
(<u>ok</u>)		θΘ				

If you do this with the above example and deactivate the third star then the fix must be the same as you got from the first two sights.

3.4. Rating the sights

It's very difficulty to estimate how accurate your 'Fix' is. Here are some error factors you must consider:

- Sextant calibration or accuracy A sextant is considered 'error free' when its index error is less then 20".
- Instability offshore You can generally estimate it around 2' but it depends to conditions off shore. When you are taking a sight always have a clear view of the horizon - avoid the wave troughs.
- Time

The sun moves a quarter of a mile each second so it's nessessary to have the correct time. I got good experience with radio controlled clocks. Also less mistakes are made with digital clocks.

You can get a better assessment from a little plot of your sights which will indicate also an inaccurate sight. Remember: the cross point of your lines is not necessarily your correct position but it is approximate. Fix accuracy is very dpendant on the azimuths of your sights which require an angle between 60 and 120 degree for the good accuracy. In addition, each new sight gives you a better position and a smaller error in your fix.

10

3.5. Changing your recorded sights

The change of sights is the standard work for sailors. Example: you take a sun sight, then continue on course. You then take another sight and get a fix. With the button 'change' you can make your last sight available as the first sight of a new fix. The new computed fix will be based on your D.R. position from that last fix. You can start with a new series of sights from here and so on. Here is an example:

D.R. 15 30 N 38 40 W 1. sight sun down 13.12.1990 UTC 10:46:29 sextant 23 6.6' 2. sight sun down 13.12.1990 UTC 14:00:14 sextant 51 0.8' no index error, height 2 m run distance 260 und 16 nm

Your fix should be

14 50.7 N 39 23.6 W

Press Change on the main menu. The 2nd sight is now the first sight in a new sequence with the fix becoming the D.R.position. The miles away or towards should be very short.

Here is the new sight:

sun down 13.12.1990 18:08:24
sextant 24 59.6'
no index error, height 2 m
run distance 260 und 24 nm

The fix is now:

14 46.3 N 39 48.0 W

3.6. Clearing your sights

The buttom 'clear' in the main menu will delete all your sights. There is no way to delete a single sight. However, you can deactive a sight through use the Sights button in the main menu and press +/- to select the required sight.

3.7. Computing a star's bearing

Take the first example for the following.

Most navigators like to prepare their sextant before taking a sight. To do this input

2001/09/05

the data as usual. However you cannot input the sextant angle as you don't know it yet. Press the '?' to get the value. If you do this with a star you also will get a bearing.

3.8. Computing a course and distance

Select 'course'. Input your initial position and your target position and Astro will compute the course and the distance.

For example: You want to go from your last fix to St. Lucia. Choose the 'course' buttom in the main menu. As you have previously taken a fix you can select the fix data by pressing 'old'. Then you only have to put in your destination data.

pos:	lat:	14	46.3 N	
	long:	39	48.0 W	
target:	lat:	14	2.0 N	
	long:	61	1.0 W	
course	270.6			
distance	1233.3	nm		

If you ever used a target before your may recall it by pressing the 2nd 'old' button.

3.9. Computing a new position

This is the opposite of 'course'. Select 'destination'. Input your position, the course, and the distance and Astro will compute the new position. Use only distances less then 500 miles for this (due mid latitude computing).

Using the same example for this you sailed 30 miles with the course 260 degree.

	Astronavigation 🚯
lat	13 42.5 N S (old)
long	45 4.7 W E
course	260
dist.	30
lat	13° 37.3' N
long	45° 35.1' W
(Ok)	(compute)

If you have calculated a fix before you may recall it now (press the 'old' button). The result also is saved and may by similarly recalled by the 'old' button. In this way you may continue computing destinations.

3.10. Noon

This computes some useful times of the day: local noon, sunrise, sunset, and the twilight times.

	Ast	ronavig	ation	i
lat long	24.23	N S W I	5 (5	old)
date high U1	11 30 FC	199 13:9:58	U	
sunrise	!	7:47:26	6:5	4:54
sunset		18:32:31 0·28·0	I 18:	57:2
(willight	L.	0.20.0	comput	0

3.11. Change the year

Astro uses its own year for the sight calculations. You set Astro's year independently of the PDA's date. Select 'year' from the main screen.

13

4. High altitude sights

Get the time for local noon at your supposed position ('noon' at main menu) and take a sight at this time. Now reduce the sight. You will get the miles away or towards the sun (due South or due North). You only have to add the miles to your D.R. latitude (away = +, towards = -).

An example (clear all old sights first):

D.R. 14 0.0 N 56 0.0 W noon at 20.12.90 15:42:00 sextant 52 30.2' Index 0.0' height 2 m

The miles are 9.1 towards.

lat -	14	0.0' 9.1'	Ν
lat at noor	n 13	50.9'	 N

If you select 'Ok' this will be saved as a new sight.

5. The average of sights

Especially in the case of strong waves the accuracy of sights is going to be reduced. For this reason take additional sights. You don't have to average them, just put them into your program and let the computer do the work. For one sun series you don't have a correct fix but with another later series you can get a nice little fix.

An example (remember to clear the old data first):

D.F	ર.	16 45.0	N	
		34 23.0	W	
1.	sight	sun down	11.12.90	10:21:32
		sextant	21 8.2	
2.	sight	sun down	11.12.90	10:23:17
		sextant	21 29.3	
3.	sight	sun down	11.12.90	10:25:38
		sextant	21 55.0	
4.	sight	sun down	11.12.90	10:27:50
		sextant	22 30.0	
5.	sight	sun down	11.12.90	10:30:07
		sextant	22 51.1	
rur	ı distan	ce course	e 250	
		nm	15	
Sor	ne more	sights:		
б.				
	sight	sun down	11.12.90	13:30:18
	sight	sun down sextant	11.12.90 49 2.0	13:30:18
7.	sight sight	sun down sextant sun down	11.12.90 49 2.0 11.12.90	13:30:18 13:34:02
7.	sight sight	sun down sextant sun down sextant	11.12.90 49 2.0 11.12.90 49 19.0	13:30:18 13:34:02
7. 8.	sight sight sight	sun down sextant sun down sextant sun down	11.12.90 49 2.0 11.12.90 49 19.0 11.12.90	13:30:18 13:34:02 13:37:13
7. 8.	sight sight sight	sun down sextant sun down sextant sun down sextant	11.12.90 49 2.0 11.12.90 49 19.0 11.12.90 49 31.4	13:30:18 13:34:02 13:37:13
7. 8. 9.	sight sight sight sight	sun down sextant sun down sextant sun down sextant sun down	11.12.90 49 2.0 11.12.90 49 19.0 11.12.90 49 31.4 11.12.90	13:30:18 13:34:02 13:37:13 13:40:32
7. 8. 9.	sight sight sight sight	sun down sextant sun down sextant sun down sextant sun down sextant	11.12.90 49 2.0 11.12.90 49 19.0 11.12.90 49 31.4 11.12.90 49 41.2	13:30:18 13:34:02 13:37:13 13:40:32
7. 8. 9.	sight sight sight sight . sight	sun down sextant sun down sextant sun down sextant sun down sextant sun down	11.12.90 49 2.0 11.12.90 49 19.0 11.12.90 49 31.4 11.12.90 49 41.2 11.12.90	13:30:18 13:34:02 13:37:13 13:40:32 13:44:24

>From 10 sights you get this fix:

16	19.9	Ν
34	50.7	W

Now select 'lines' in the fix page and examine distance values. We will now deactivate the sights with the largest offsets. When you deactivate the sight 4 (5.7 nm) you will get a better standard deviation. Going on with the 6. sight (4.7 nm) the deviation is further reduced.

> 16 18.2 N 34 53.6 W

Please be careful. The angle between the two azimuths is very low. It's better to have an azimuth value of more then 40 degrees.

15

Appendix

Some examples

Use the year 1990 for all.

for	all use	index error = 0.0'
		height = 2 metres
1.	D.R.	25 18 N
		18 6 W
	1. sight	sun down 28.11.90 UTC 16.53.02
	0 1 1	sextant 16 40.4
	2. sight	moon up 28.11.90 UTC 16.56.18
		sextant 22 35
	new pos.	25 25.5 N 18 15 1 W
2	ΠR	24 23 N
4.	D.R.	20 20 W
	1. sight	unknown star 30.11.90 UTC 7.05.42
	1. 21910	bearing 120 sextant 32 41.4
	2. siqht	unknown star 30.11.90 UTC 7.12.14
	5	bearing 230 sextant 22 29.8
	position	24 5.9 N the star are spica and
		20 32.1 W sirius.
3.	D.R.	13 43 N
		44 31 W
	l. sight	mars 16.12.90 UTC 21.33.30
	2 gight	Sextant 39 29.4
	Z. SIGHU	achernar 16, 12, 90 UIC 21, 30, 10
	position	14 38 3 N
	POSICION	44 555 W (verv bad)
4.	D.R.	14 15 N
	2	56 7 W
	1. sight	venus 25.12.90 UTC 21.56.20
		sextant 4 54.2
	2. sight	vega 25.12.90 UTC 22.01.54
		sextant 9 23.8
	position	14 4.9 N
-		56 7.1 W
5.	Examples ic	or a running fix
	D.R.	39 40 N 15 20 F
	1 sight	$13 \ 20 \ E$
	I. SIGIIC	Sextant $16 20.6$
	run distand	re 336 8 nm
	2. sight	sun down 14.07.1990 UTC 7:26:53
		sextant 40 30.0
	fix	39 26.0 N please notice the
		15 16.8 E very short time between
		the sights
	Now change	the 2nd sight to become the first position
	new sight	202 0.4
	run distand	ce 323 9.4 nm
	signt	sun aown 14.07.1990 UTC 9:44:23

2001/09/05

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AstroNavigation

16

sextant 64 54.3 new fix 39 40.7 N 15 10.3 E Now change the 2nd sight to become the first position again new sight run distance 323 7.4 nm sight sun down 14.07.1990 UTC 11:10:22 sextant 71 39.6 new fix 39 46.6 N 15 4.4 E

Addenda

I tested his program offshore for one year. For the reference I used various nautical almanacs, a GPS receiver and the logs of some friends. I believe that the compiled positions are relatively error free. But I can't give you any 100% guarantee that your positions are correct. Be careful with the output and, like all good navigators, use common sense and always cross-check your fixes an position by other methods and systems.

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